Single Pilot Resource Management (SRM) Crew Resource Management (CRM)

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These callouts should be memorized and practiced during flight.
When flying with two pilots, the pilot flying flies the airplane, and the pilot monitoring calls these out.

Condition / Location		Pilot Flying (PF) or Pilot Monitoring (PM)
Engine Starting	During Engine Start	*"oil pressure"*
	During Takeoff	*"power normal" or "abort"*
Anytime	Airspeed 5 knots or more below target airspeed	*"airspeed"*
	Altitude 200 feet above or below target	*"altitude"*
Climb	1000 ft below assigned altitude	*"one thousand to go"*
Descent	1000 ft above assigned altitude	*"one thousand to go"*
Descent	VSI exceeds 1200 feet per minute	*"sink rate"*
Approach	First Positive Inward motion of localizer needle	*"localizer alive"* or *"course alive"* (when captured, "localizer" or "course" captured")
	First Positive motion of glideslope needle	*"glideslope alive"* (when captured, "glideslope" or "glidepath" captured")
	If more that one dot from GS/GP	*"glideslope"* or *"glidepath"*
	If more that one dot from Localizer	*"localizer"* or *"course"*
	Visual Descent Point	*"VDP"*
	200' above minimums	*"200' above"*
	100' above minimums	*"100' above"*
	Reaching Decision Height, Minimum Descent Altitude, or Missed Approach Point	*"minimums"* or *"approach/lights"* or *"runway in sight"* or *"no runway missed approach"*
	Loosing Runway Environment	*"missed approach"*
Transfer of Controls		Pilot flying *"Your Controls"* followed by pilot monitoring acknowledgment *"My Controls"*
Autopilot On	HDG or NAV	*"Autopilot Engaged HEADING"* or *"Autopilot Engaged NAV"*
	VS	*"Vertical Speed XXX FPM Climb Altitude Armed"* or *"Vertical Speed XXX FPM Descent Altitude Armed"*
	APP	*"Approach Armed" "Approach Captured" "Glideslope Armed" "Glideslope Captured"*
Autopilot Off		*"Autopilot Disengaged"*